

Vari-Vert 40-6 Meters

A Flagpole'ish Antenna

Excerpt from the TVARC presentation of February 2017

by

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An “*Electrically*” Variable Vertical

The design, construction and performance of an inexpensive “Low Observable” antenna that provides 40-6 Meter capability.

- The antenna ‘looks like’ and performs like a Flagpole.
- 20’ Flagpoles are allowed in Florida by State Statute [720.304](#) (2b).
- Commercial antennas with controllable length elements are expensive and generally require maintenance or repair *by the manufacturer*.
- The following slides deal with an electrically similar homebrew antenna that is simple to build and easy to maintain.

Flagpole Type Verticals

20' Flagpole, Non-Resonant (in ham bands)

- Requires a Remote Tuner at the antenna, OK
- Tuner In Operator Location, Not so good....

$\frac{1}{4} \lambda$ Resonant Vertical, so.... No Tuner
(aka; Marconi antenna)

Thinking.... SteppIR Vertical? You are close!

Trade-Off's

Flagpole Radiator

- Remote Tuner ***Required***

- 100 watt class or big \$\$\$
- Tuner is somewhat delicate
- Tuner loss, moderate
- Cost ~\$350
 - Aluminum Flagpole
 - Tuner
 - Bias T

$\frac{1}{4} \lambda$ Resonant Radiator

- No Tuner

- Legal Limit, **No Tuner Loss**
- Simple Mechanics
- No critical dimensions
- Cost~\$350

- Carbon Fiber Pole

- Homebrew Mechanics
- Enclosures, Micro Processor/Display,
- Bias T

Not a clear winner..... BUT

If any repair is needed you can do it yourself after all you built it.
A sense of accomplishment is worth something! Great talking point

The Vari-Vert

Parameters:

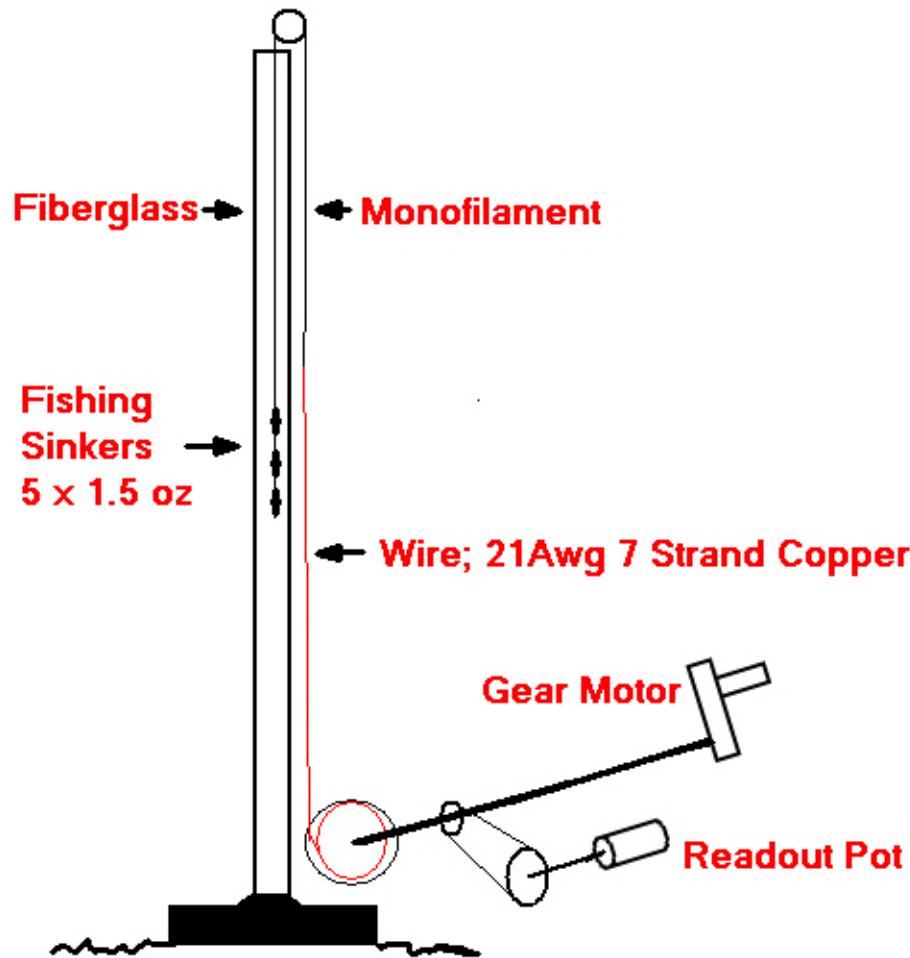
- True $\frac{1}{4} \lambda$ Antenna
- Low Angle for DX op's
- 20 - 6 Meters **– - No Tuner needed**
- 40-30 Meters uses 2 relays and a tapped L, fixed C
- Digital Control / Readout Unit
- Build it all for ~\$350

Uses inexpensive, readily available component parts

Tools; a Dremel Rotary, a Soldering Iron and household tools

Vari-Vert Layout

Prototype Configuration



“Fiberglass” Flagpole Material Properties

Carbon Fiber, non-conductive, ideal antenna support

Carbon Fiber and Aluminum similar strength

Deflection for 20', 2"dia, 0.125 wall, 1# Force

| Deflection calculator for round tube beams | |
|---|--|
| Input | Output |
| Length (inches) <input type="text" value="240"/> | Aluminum 1.42" |
| Diameter (inches) <input type="text" value="2"/> | Deflection (inches) <input type="text" value="1.417793021798"/> |
| Wall thickness (inches) <input type="text" value=".125"/> | Bending Stress (psi) <input type="text" value="738.4338655200"/> |
| Force (pounds) <input type="text" value="1"/> | Energy (joules) <input type="text" value="0.080093711729"/> |
| Material <input type="button" value="Aluminum"/> | |

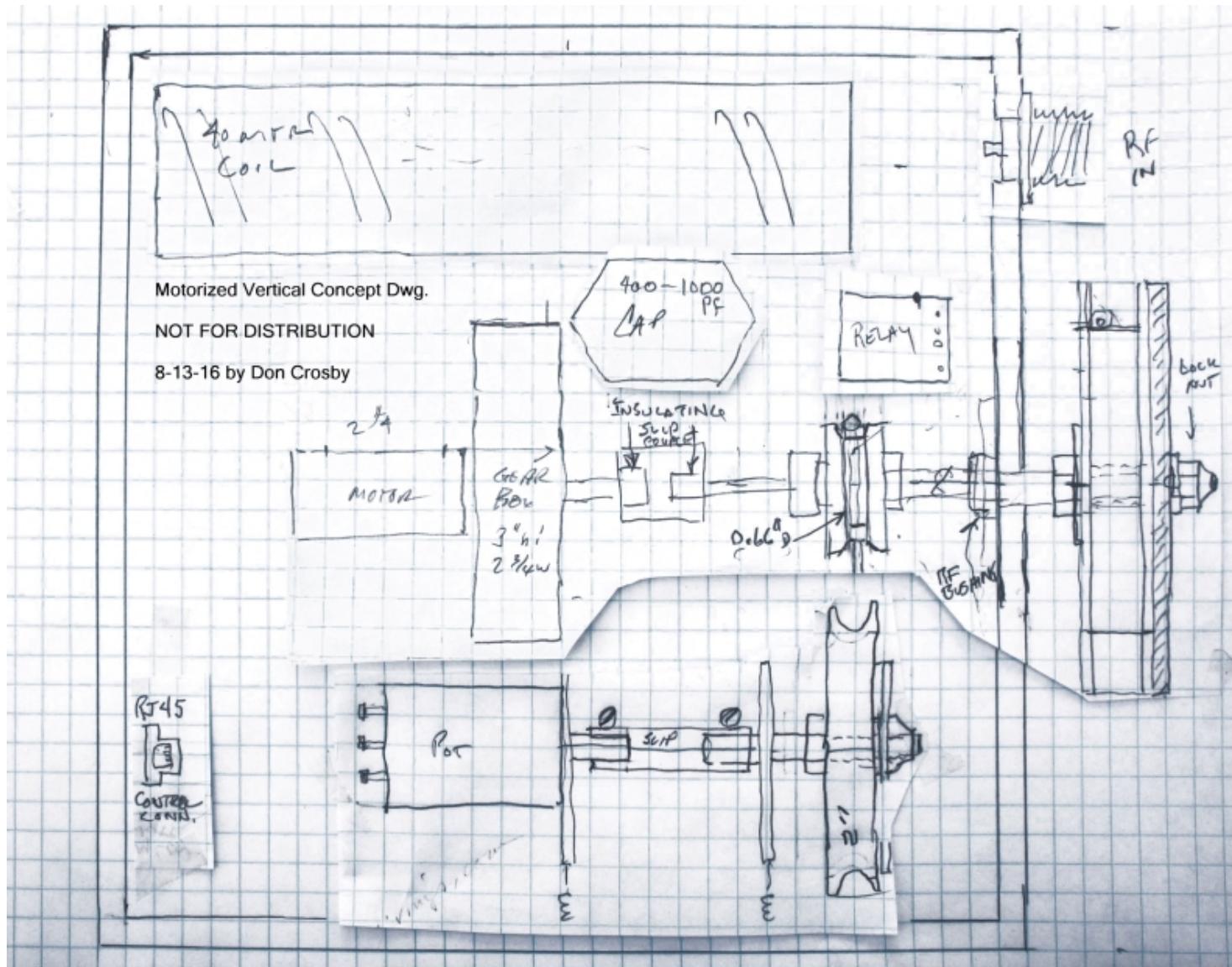
| Deflection calculator for round tube beams | |
|--|--|
| Input | Output |
| Length (inches) <input type="text" value="240"/> | Carbon Fiber 1.4" |
| Diameter (inches) <input type="text" value="2"/> | Deflection (inches) <input type="text" value="1.396840415564"/> |
| Wall thickness (inches) <input type="text" value=".125"/> | Bending Stress (psi) <input type="text" value="738.4338655200"/> |
| Force (pounds) <input type="text" value="1"/> | Energy (joules) <input type="text" value="0.078910060816"/> |
| Material <input type="button" value="Std. Carbon Fiber Fabric"/> | |

Mast Components

- Fiberglass Pipe 8' by 1.5", 1.75", 2"dia.
- Homebrew Low Friction Pulley
- Hose Clamps between pipe sections

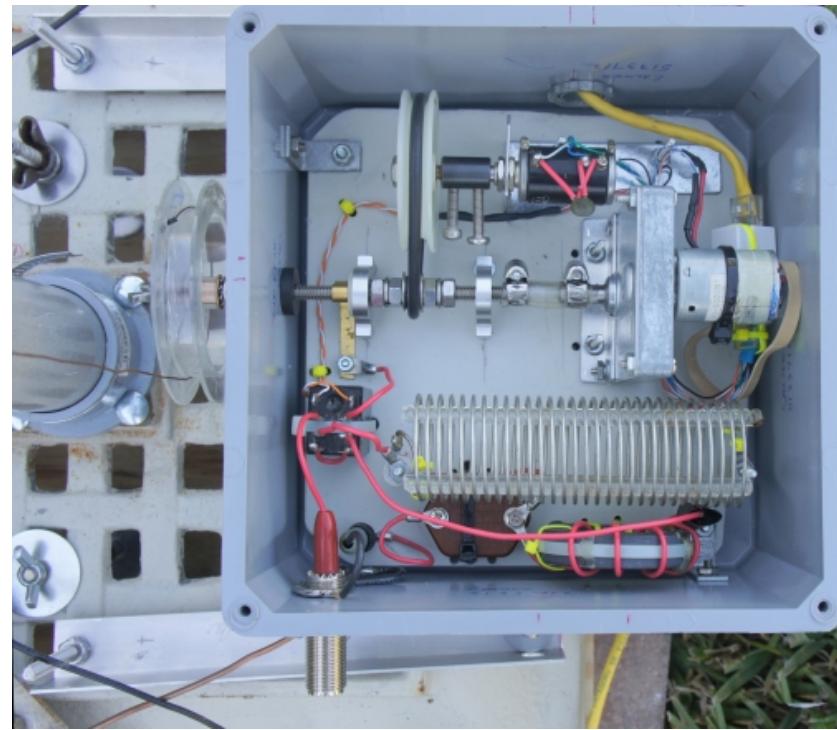


Vari-Vert Mechanism Layout



Vari-Vert “All-Up”

- Radiating wire length is set for $\frac{1}{4} \lambda$



Vari-Vert Component Trade-Off's

Motor Options

- Brush Type DC,
- Brushless DC,
- Stepper,
- AC

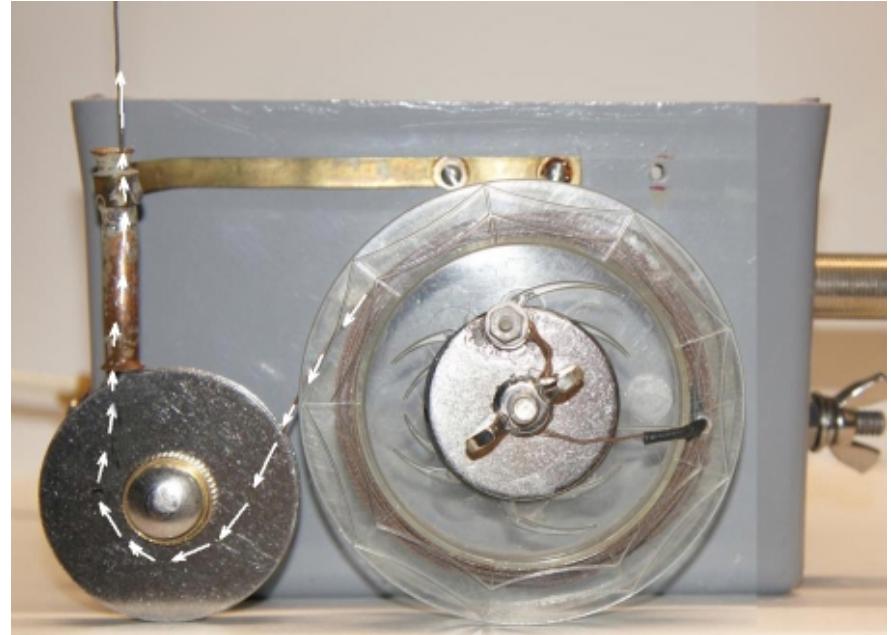
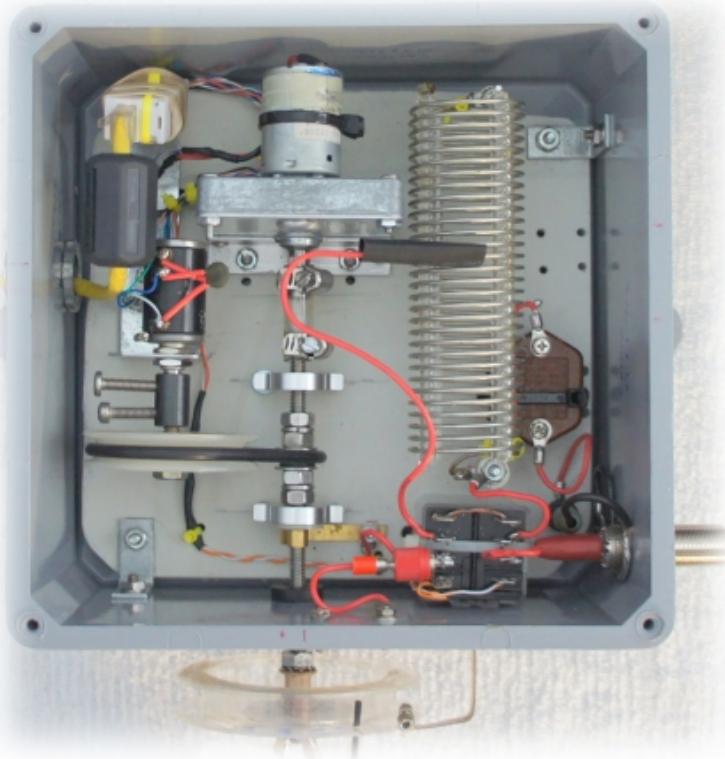
Sensor Options

- Multi-Turn Potentiometer
- Incremental Encoder
- Absolute Encoder \$\$\$
- Mechanical Counter

I just used things on hand.

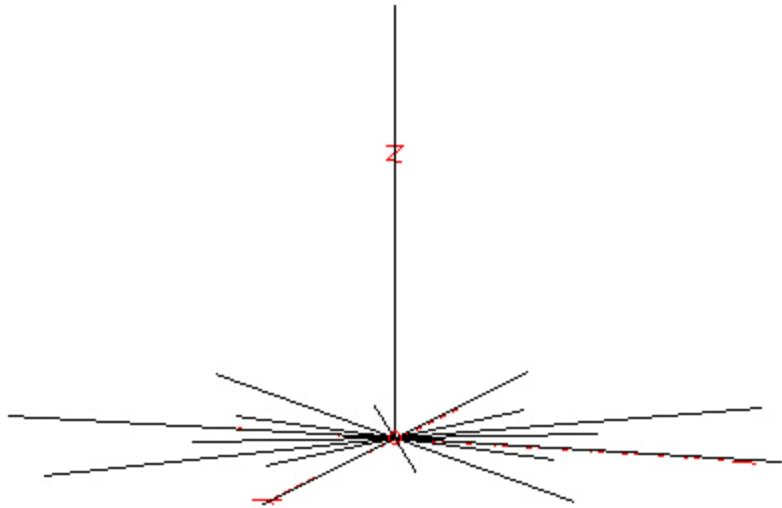
- Brush Type DC Motor
- Multi-Turn Potentiometer

Remote Motor Box



Antenna wire “pays” off the spool and makes additional RF contact with the brass pulley and copper guide.

Model Layout

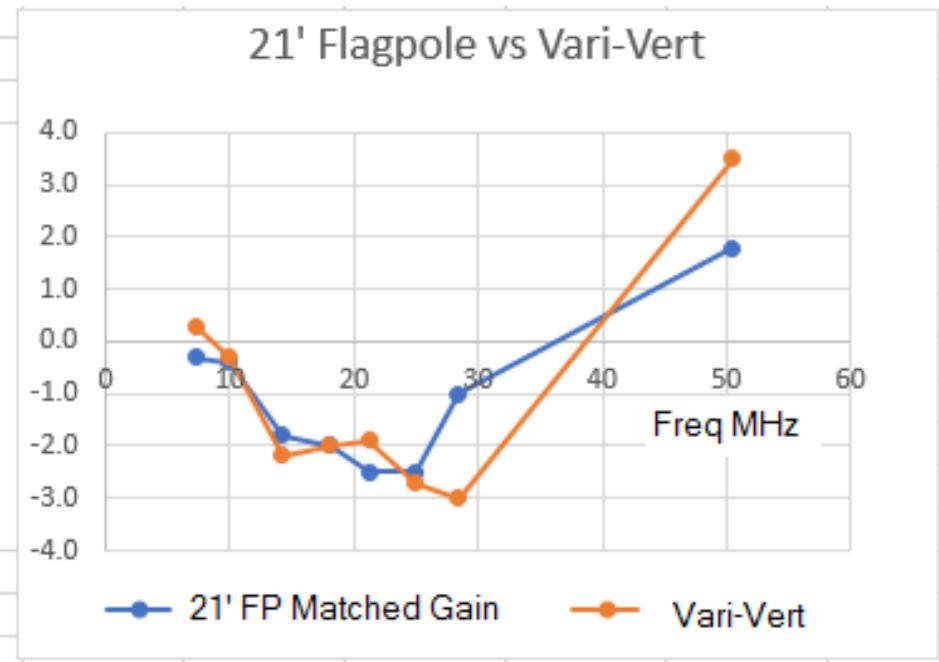


Height is Variable
Radials 8-10' & 8-20' @
1" above Ground *for Model* *
Average Soil C=5ms, Er=13
Nec2 Modeling Engine

- * The NEC-2 Modeling Engine does not permit wires below ground, but comparisons by L.B. Cebik W4RNL (SK) indicate above ground provides good correspondence

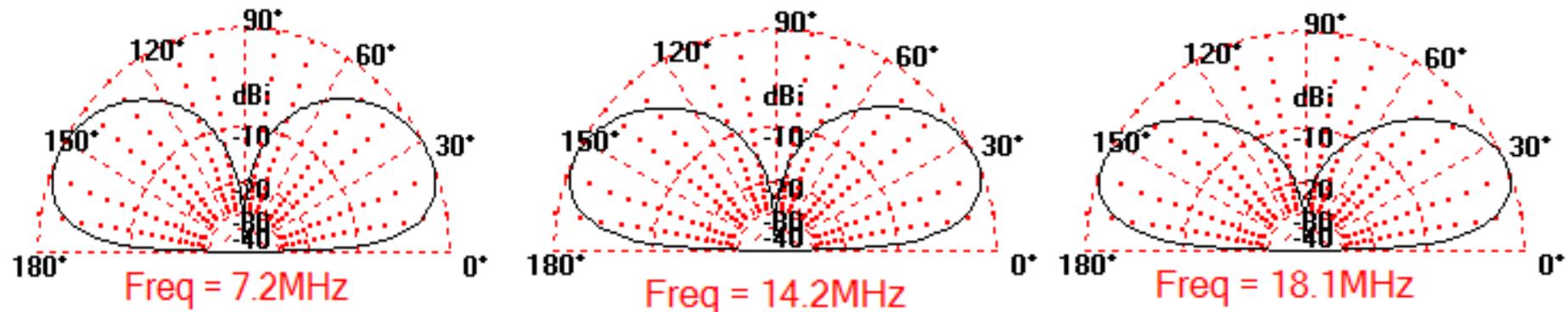
NEC2 Modeling Predictions

| F-MHz | 21' FP Matched Gain | Vari-Vert Gain dbi |
|-------|------------------------|-----------------------|
| 7.2 | -0.3 | 0.3 |
| 10 | -0.4 | -0.3 |
| 14.2 | -1.8 | -2.2 |
| 18.1 | -2.0 | -2.0 |
| 21.2 | -2.5 | -1.9 |
| 25 | -2.5 | -2.7 |
| 28.4 | -1.0 | -3.0 |
| 50.5 | 1.8 | 3.5 |

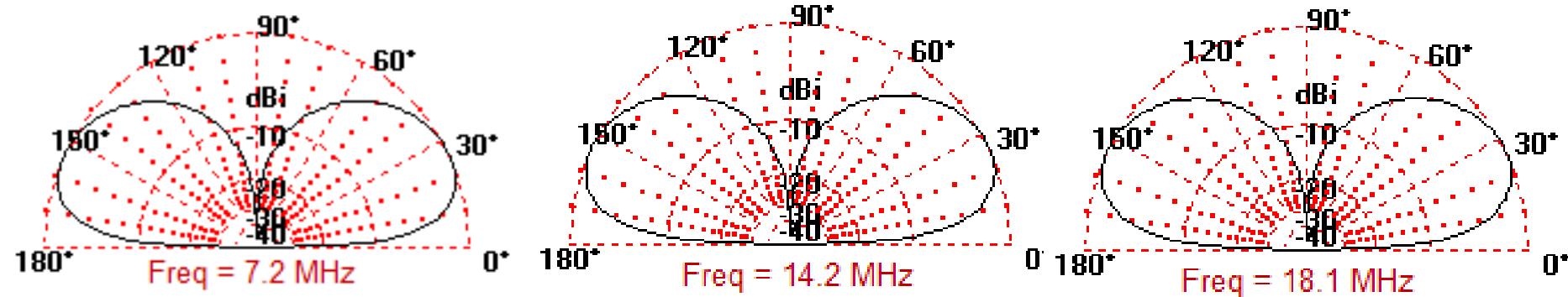


- 21' Flagpole with Tuner to Match at the FP Base
- Vari-Vert Radiator Length set to $\frac{1}{4}\lambda$ by remote
- **Note:** Vari-Vert acts as $\frac{3}{2}\lambda$ at 50.5 MHz

7.2, 14.2, and 18.1Mhz Elevation Plots Shapes



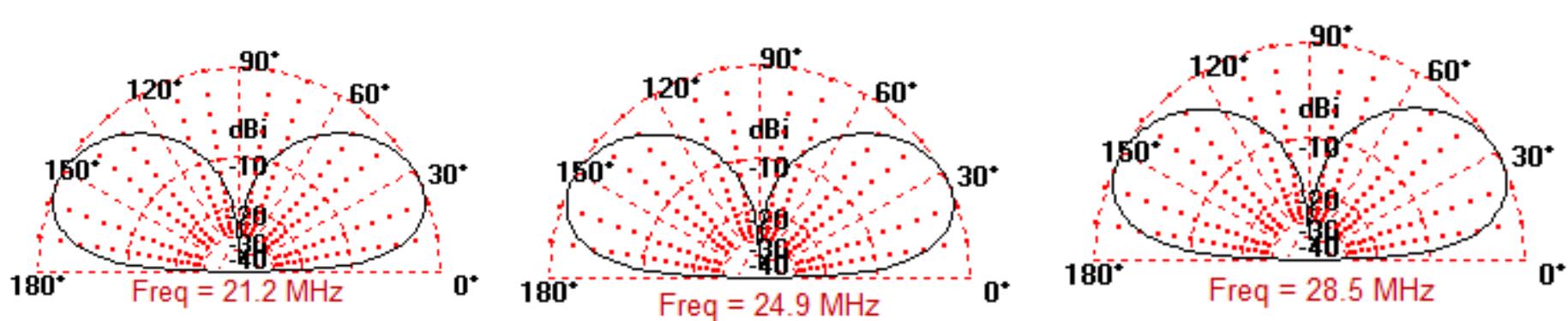
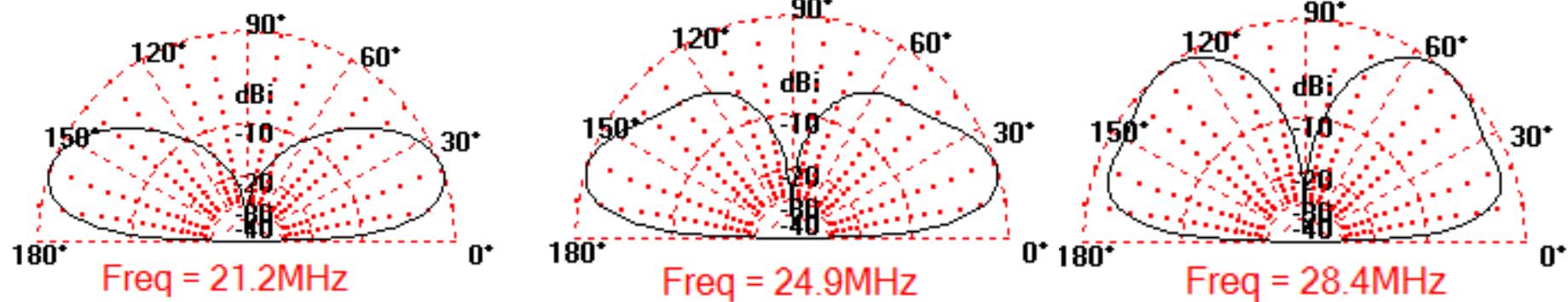
21' Flagpole



Outer Ring -0.28 dBi
C-L Lo Pass L-Net,
682.71 pF, 8.17 uH

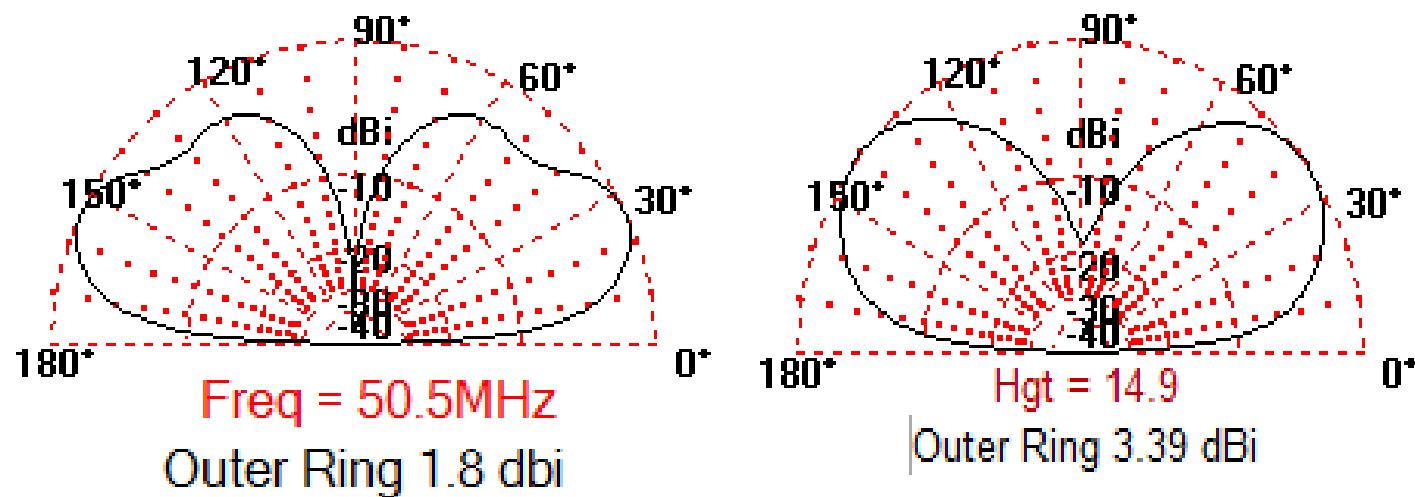
Vari-Length Vertical $\frac{1}{4}\lambda$

21.2, 24.9, and 28.5Mhz Elevation Plots Shapes



Vari-Length Vertical

50.5 MHz



21' Flagpole

14.7' Vari-L $\frac{3}{4} \lambda$

6 Meters the Vari-Vert works as a $\frac{3}{4} \lambda$ vertical

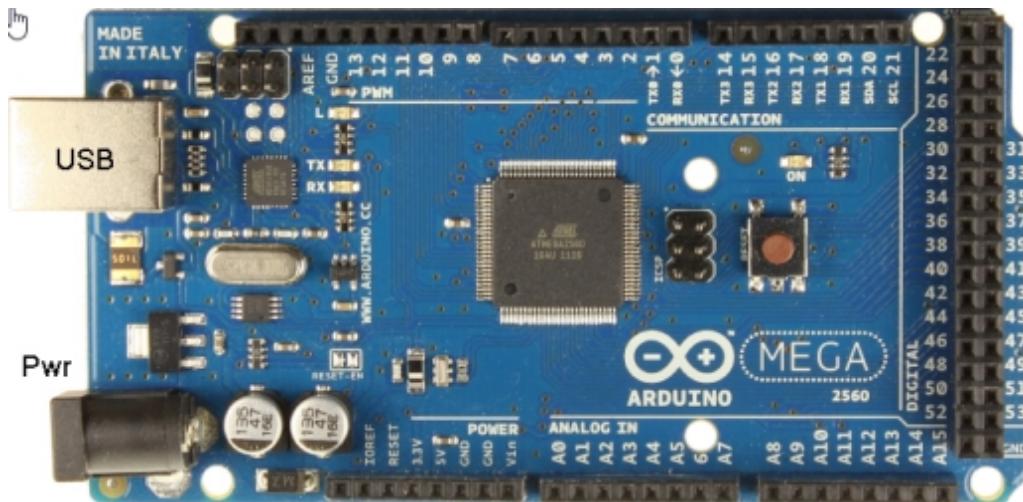
Provides ~ 1.6 db Gain overall advantage

Desktop Controller

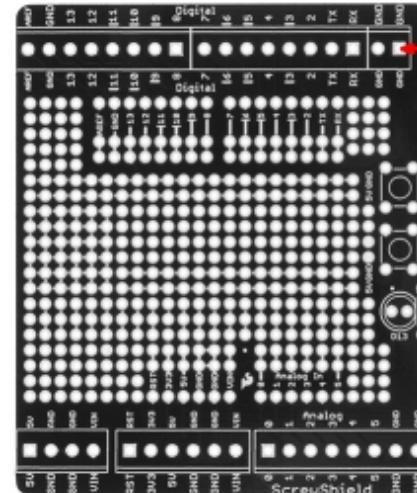
Requirements:

- Digital display of Frequency and Length
- Smooth motor speed ramping
- Expandable functions and inexpensive
- Future features....
 - Pushbutton command to calibrate the radiator length *
 - Stall sensor motor shutdown *

Controller Components



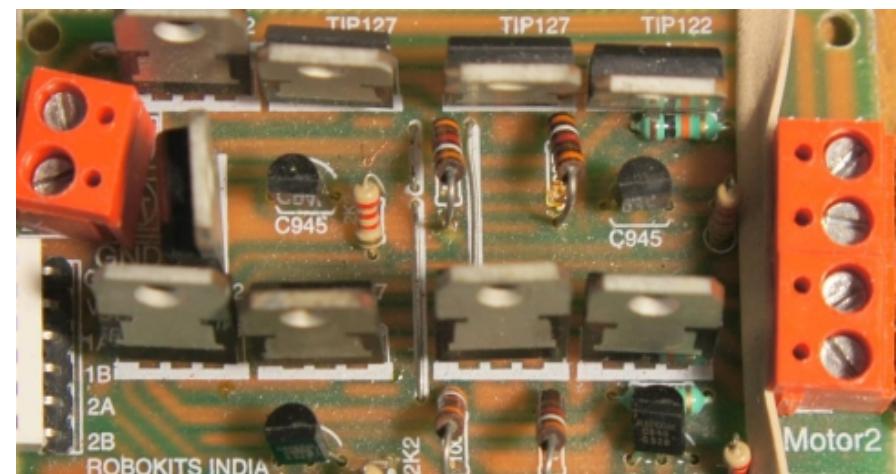
Arduino Mega 2560 \$12



Breakout Board \$15

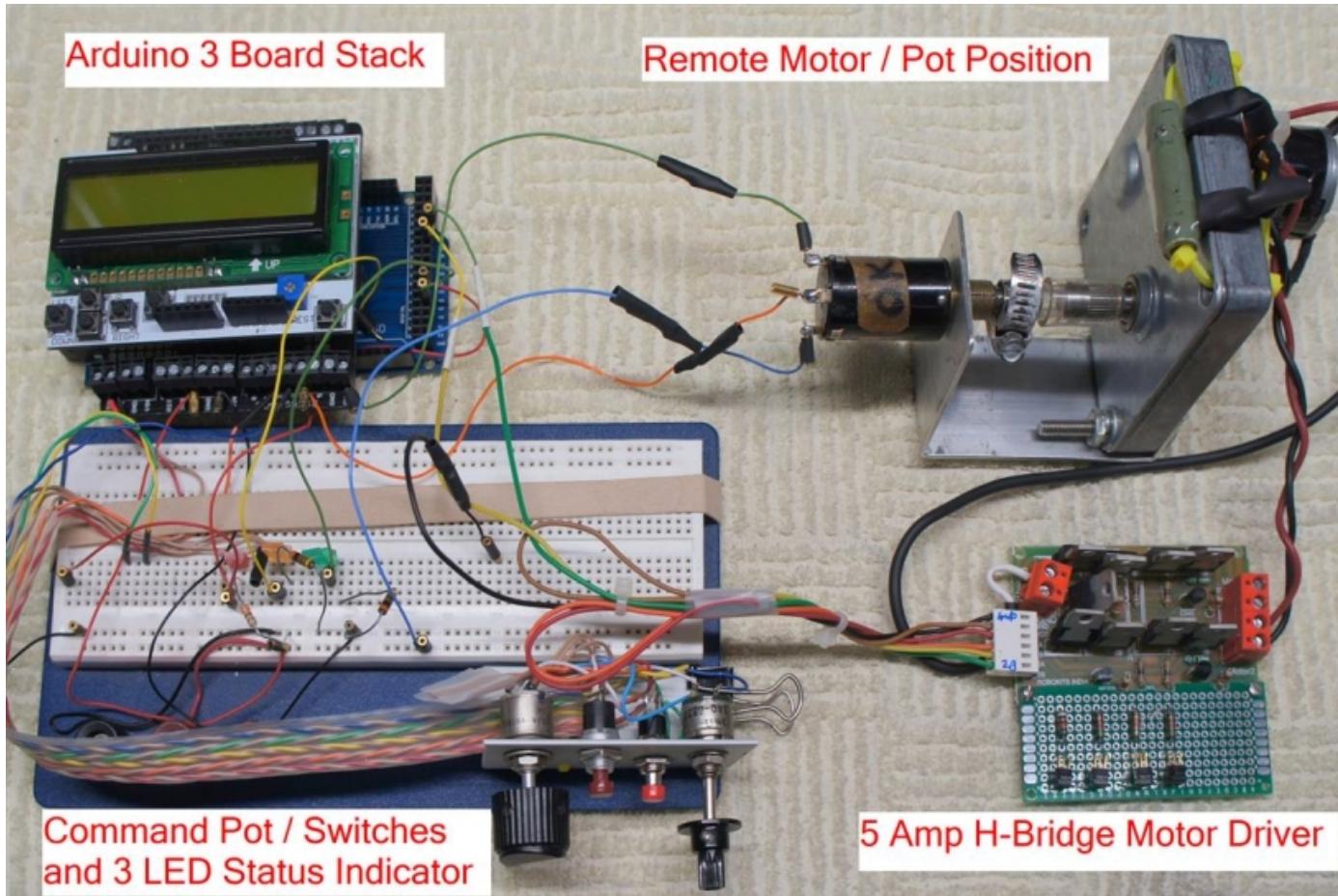


2x16 Backlit LCD \$13



Dual H Bridge Motor Driver \$5

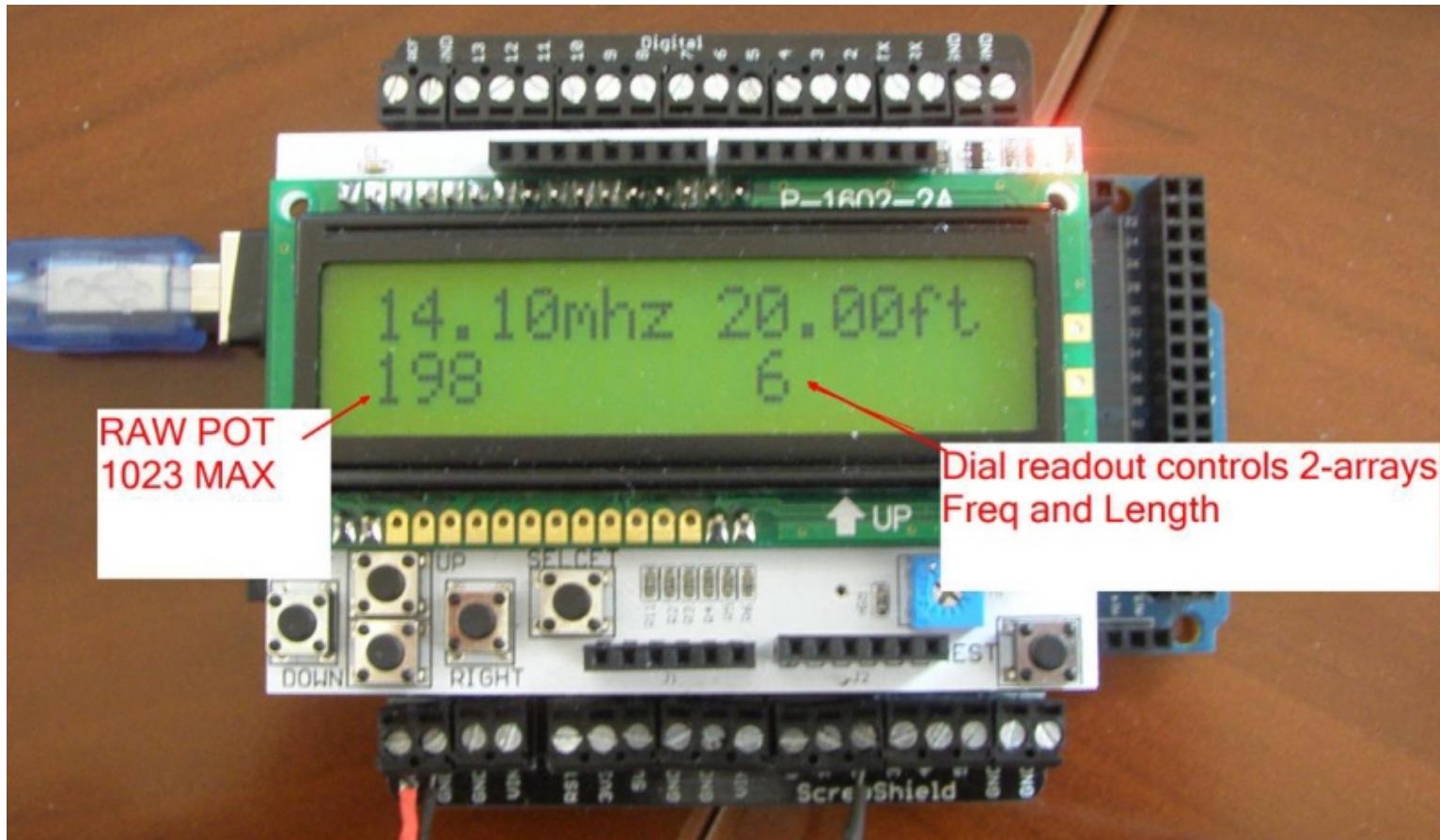
Controller Breadboard



Arduino Development Program (Free)

Connectivity by USB to the 3 board stack

Display Readout



“The Programmer IDE... PC or MAC”

IDE means.. Integrated Development Environment

- Features

- “Sketch” entry for typing in your program code
- Details any errors it uncovers in the code
- Compiles and loads the code to the target computer board
- Calculates memory usage
- Provides Serial Monitor for debugging
- Powers up the hardware through the USB

- Arduino IDE is a FREE download

- Lots of shared software “sketches” on the web
- Good ‘forum’ support for beginners
- Lots of easy projects to get your feet wet

Field Experience

- Operated at a local hams QTH during Nov – Dec 2016
- Good contacts and on-the-air reports operating CW at 3-5 watts
- Experienced mechanical hang-ups due to the jerky start / stop motion

As Demo'ed at the TVARC Meeting

- Microprocessor Smart Controller was designed during the field evaluation period.
- Microprocessor code was written debugged and readied for testing
- The micro processor provided smooth start/run/stop and resolved the hang-ups

Interested in more info about this antenna?

Don, W1EJM

- QRZ.com
- Phone book
- 443.150MHz